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	Original Submission
Vladimir Stojanovic (Reviewer 1)	Revisions
(Reviewer 2)	Major revisions
Author	Response to Reviewers

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From: em.nody.0.53f0a9.7d501c24@editorialmanager.com on behalf of Nonlinear Dynamics (NODY) <em@editorialmanager.com>
Sent: 29. april 2016 15:13
To: Vladimir Stojanovic
Subject: Thank You

Dear Dr. Stojanovic,

Thank you very much for your review of manuscript

NODY-D-16-00335, "Robust adaptive unscented Kalman filter for nanosat attitude estimation".

We greatly appreciate your assistance.

With kind regards,

Journals Editorial Office

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